

MS 15 EXPOSED LINEAR ENCODERS WITH HOMING AND LIMIT FUNCTION







SPECIAL FEATURES

- Online signal stabilization
- Display of the signal quality directly at the scanning head via 3-coloured LED function
- Permanent control of the signals over the whole measuring length
- High quality of the signals due to singlefield scanning
- Homing and limit function
- Reference mark position customizable

PERFORMANCE CHARACTERISTICS

- CONTAMINATION RESISTANCE
- IMMUNITY AGAINST AGING AND TEMPERATURE CHANGES
- HIGH PERMISSIBLE TRAVERSING SPEED
- EASY MOUNTING
- SMALL DIMENSIONS
- NO MECHANICAL BACKLASH
- NO FRICTIONAL FORCE
- REFERENCE MARKS REPEATABLE FROM BOTH TRAVERSING DIRECTIONS
- TWO SEPARATE SWITCH SIGNALS
- RESOLUTION: 10 μm 0.05 μm

MS 15 MEETS ALL THESE REQUIREMENTS!



TERM EXPLANATIONS

Grating period

A grating is a continuous series of lines and spaces printed on the graduation carrier. The width of one line and one space is called the period of the grating. The lines and spaces are accurately placed on the graduation carrier.

Signal period

When scanning the grating, the scanning head produces sinusoidal signals with a period equal to the grating period.

Interpolation

The sinusoidal signal period can be electronically divided into equal parts. The interpolation circuitry generates a square-wave edge for each division.

Measuring step

The smallest digital counting step produced by an encoder.

Yaw angle, pitch angle, roll angle, displacement, gap tolerance

Mounting tolerances of the scanning head relative to the graduation carrier.

Reference pulse (reference mark)

There is an additional track of marks printed next to the grating to allow a user to find an absolute position along the length of the graduation carrier. A one increment wide signal is generated when the scanning head passes the reference mark on the graduation carrier.

This is called a "true" reference mark since it is repeatable in both directions. Subsequent electronics use this pulse to assign a preset value to the absolute reference mark position.

Error signal (US)

This signal appears when a malfunctioning encoder generates faulty scanning signals.

Online signal stabilization (HSP)

During moving the amplitude, offset-error, amplitude differences and phase shift error are measured and stabilized cyclic.

Abbe error

Measuring error due to lateral distance between the measuring system and the machining level.

SCANNING PRINCIPLE

The model MS 15 incremental linear encoder system works with the photoelectric measuring principle and a **singlefield reflective scanning method**.

The regulated light of an infrared LED is collimated by a condenser lens and passes through the grid of the reticle. After being reflected from the graduation carrier, the infrared LED generates a periodic intensity distribution on the structured sensor.

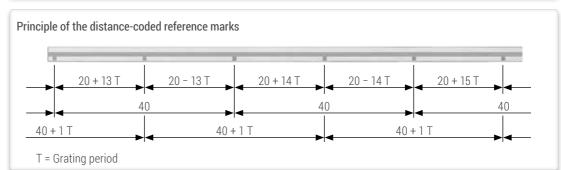
The sensor generates high quality sinusoidal signals which are highly insensitive to possible contaminations.

The regulation of the LED ensures a constant signal amplitude, guaranteeing stability in the case of temperature fluctuations and with long-run operation.

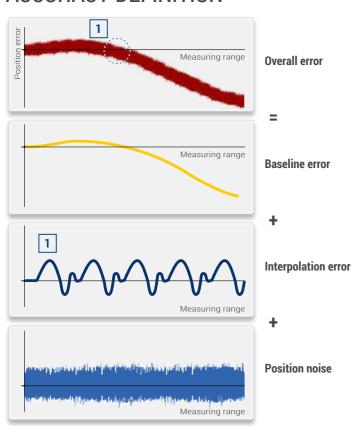


REFERENCE MARKS





ACCURACY DEFINITION

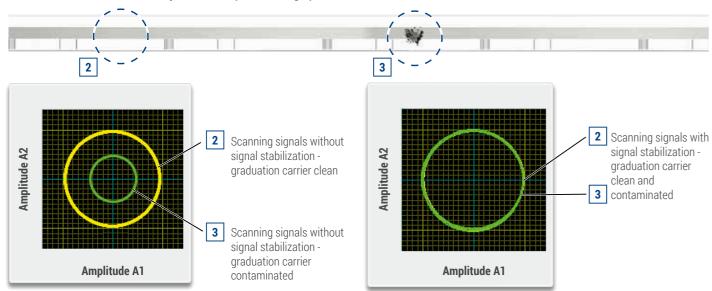


The accuracy of a linear encoder is mainly determined by the baseline error of the graduation carrier, the interpolation error of the optoelectronic scanning and the position noise.

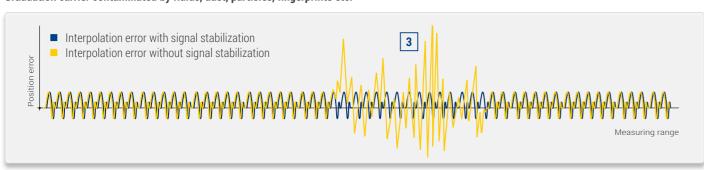
The baseline error is the error of the graduation carrier identified in a measurement room under optimum conditions, along a determined measuring length, without any interpolation error and position noise.

The indicated accuracy grade represents the maximum possible baseline error. It is calculated within any section with a maximum length of one meter.

Effect of contamination on the quality and amplitude of scanning signal Graduation carrier contaminated by fluids, dust, particles, fingerprints etc.



Effect of contamination on the interpolation error Graduation carrier contaminated by fluids, dust, particles, fingerprints etc.



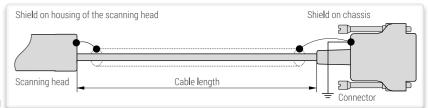
SHIELDING, PIN ASSIGNMENT







Shielded PUR-cable; Bending radius Bending radius
Drag chain qualified. fixed mounting continuous flexing



D-sub connector, male, 15-pin

Pin	1	2	3	4		6	7	8		10	11	12	13	14	15
Sinusoidal voltage signals 1 Vpp	Test**	0 V Sensor	Occupied	RI-	A2-	A1-	V+ Sensor	V+	0 V	S1***	S2***	RI+	A2+	A1+	nc
Square-wave signals via line driver	Test*	0 V Sensor	US	RI	T2	Tī	V+ Sensor	V+	0 V	S1***	S2***	RI	T2	T1	nc

- * Test = analog signal switch-over for set-up.
 By applying +5 V to the test pin, the test signals (sinusoidal micro-current signals 11 μApp) are switched to the output connector.
- ** Test = analog signal switch-over for set-up.

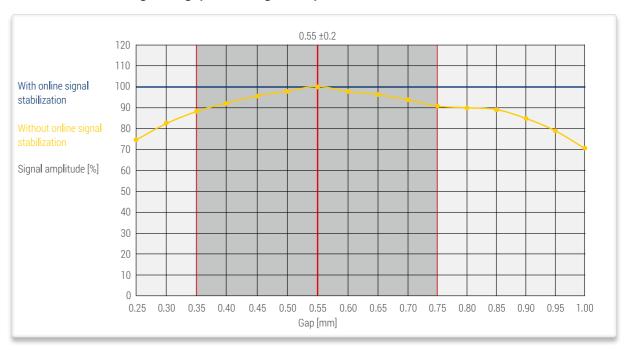
 By applying +5 V to the test pin, the NOT corrected test signals (1 Vpp) are switched to the output connector.
- S1, S2 = switch signals.
- *** Version without switch signals (version K) = without function.
- Sensor: the sensor pins are bridged in the chassis with the particular power supply.
- The shield is connected with the chassis.
- Pins or wires marked "occupied" or "nc" must not be used by the customer.

9 10 1112 13 14 15 Mass: 28 q

Pin assignment

(view on pins)

Effect of the scanning head gap on the signal amplitude



- 0



INTERFACES

SINUSOIDAL VOLTAGE SIGNALS 1 VPP

(drawing shows "positive counting direction")

Power supply: +5 V ±10 %, max. 160 mA (unloaded)
Track signals (differential voltage A1+ to A1- resp. A2+ to A2 -):

Signal amplitude 0.6 Vpp to 1.2 Vpp; typ. 1 Vpp

(with terminating impedance Zo = 120 Ω between A1+ to A1- resp. A2+ to A2-).

Reference mark (differential voltage RI+ to RI-):

Square-wave pulse with an amplitude of 0.8 up to 1.2 V; typical 1 V (with terminating impedance Zo = 120Ω between RI+ to RI-)

Advantage

- High permissible traversing speed with long cable lengths possible.

SQUARE-WAVE SIGNALS

(drawing shows "positive counting direction")

With the integrated interpolation electronics (for times -1, -5, -10, -20, -25, -50, -100 or -200) the photoelement output signals are converted into two square-wave signals that have a phase shift of 90°.

The output signals are "differential" via line driver (RS 422). One measuring step reflects the measuring distance between two edges of the square-wave signals.

The controls/DRO's must be able to detect each edge of the square-wave signals. The minimum edge separation a_{min} is listed in the technical data and refers to a measurement at the output of the interpolator (inside the scanning head). Propagation-time differences in the line driver, the cable and the line receiver reduce the edge separation.

Propagation-time differences:

Line driver: max. 10 ns Cable: 0.2 ns/m

Line receiver: max. 10 ns (referred to the recommended line receiver circuit)

To prevent counting errors, the controls/DRO's must be able to process the resulting edge separation.

Example:

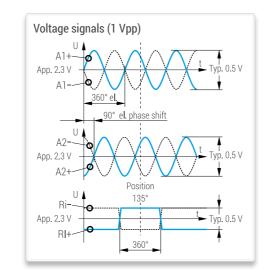
 $a_{min} = 100 \text{ ns}, 10 \text{ m cable}$

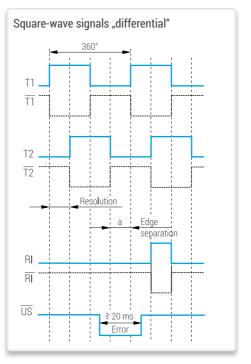
100 ns - 10 ns - 10 x 0.2 ns - 10 ns = 78 ns

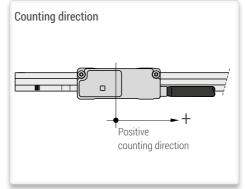
Power supply: +5 V ±10 %, max. 160 mA (unloaded)

Advantages:

- Noise immune signals.
- No further subdividing electronics necessary.

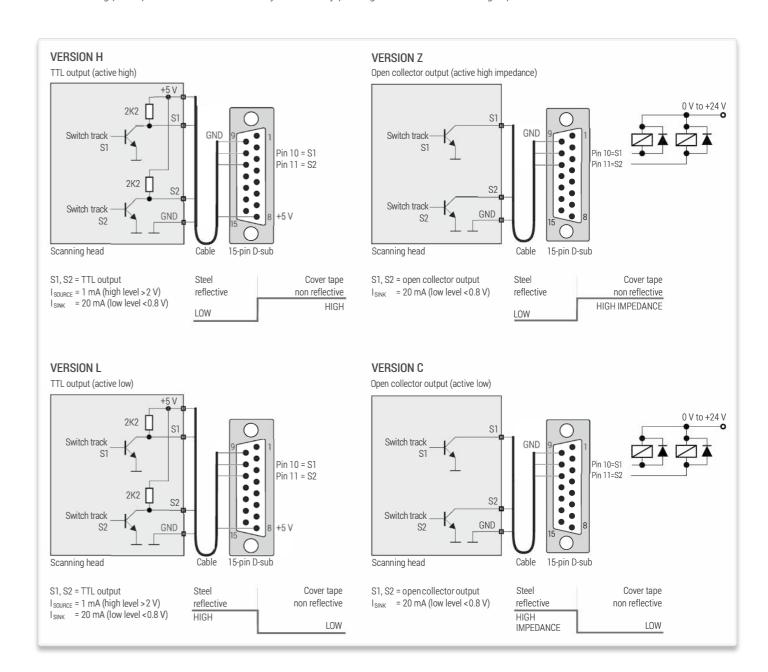






SWITCH SIGNAL OUTPUT

For individual special functions there are two additional switch tracks on the steel tape scale. The switching point position can be chosen by the user by placing self-adhesive covering tapes.



07_____



TECHNICAL DATA

SCANNING HEAD

Model	AK MS 15 1 Vpp	AK MS 15 TTLx1u	AK MS 15 TTLx5	AK MS 15 TTLx10	AK MS 15 TTLx20	AK MS 15 TTLx25	AK MS 15 TTLx50	AK MS 15 TTLx100	AK MS 15 TTLx200	
Interface	\sim	Л	Л	Л	Л	Л	Л	Л	工	
Measuring step [μm]	Depending on external interpolation	10.00	2.00	1.00	0.50	0.40	0.20	0.10	0.05	
Integrated interpolation		Times 1	Times 5	Times 10	Times 20	Times 25	Times 50	Times 100	Times 200	
Max. velocity [m/s]	10.00	10.00	6.40	3.20	2.40	1.92	1.92	0.96	0.96	
Max. output frequency	250 kHz									
Edge separation a _{min}		500 ns	300 ns	300 ns	200 ns	200 ns	100 ns	100 ns	50 ns	
Interpolation error with signal stabilization	Typical ±65 nm (peak-peak)									
Electrical connection	Cable, 0.5 m	Cable, 0.5 m, 1 m or 3 m with D-sub connector, male, 15-pin								
Voltage supply	+5 V ±10 %	+5 V ±10 %								
Power consumption	Max. 880 m	Max. 880 mW (without load)								
Current consumption	Max. 160 mA (without load)									
Vibration 55 Hz – 2000 Hz Shock 8 ms	≤ 150 m/s² (EN 60 068-2-6) ≤ 750 m/s² (EN 60 068-2-27)									
Operating temperature Storage temperature	0 °C to 50 °C -20 °C to 70 °C									
Mass	Scanning head: 12 g (without cable), cable: 30 g/m, connector: D-sub connector: 28 g									

GRADUATION CARRIER

Model	MB MS 15 MK	MS 15 MP	MS 15 GK	MS 15 BK				
Graduation carrier	Steel tape scale	Steel tape scale	Glass scale	Glass ceramic scale				
Coefficient of linear expansion	α≈ 10 x 10 ⁻⁶ /K	$\alpha \approx 10 \times 10^{-6} / K$	$\alpha \approx 8.5 \text{ x } 10^{-6}$	$\alpha \approx 0 \times 10^{-6} / K$				
Grating period	40 μm	40 μm	40 μm	40 μm				
Accuracy grades *	±5, ±15 μm/m	±5, ±15 μm/m	±3, ±5 μm/m	±3, ±5 μm/m				
Non-linearity *	±3 μm/m	±3 μm/m	±3 μm/m	±3 μm/m				
Baseline error	≤ ±0.75 µm/50 mm (typical)	≤ ±0.75 µm/50 mm (typical)	≤ ±0.30 µm/10 mm	≤ ±0.30 µm/10 mm				
Measuring length ML	20 000 mm	20 000 mm	3140 mm	1940 mm **				
Reference marks	Standard: 50 mm equidistant / Position selectable by customer / Distance-coded on request							
Mass	17 g/m	90 g/m + 2 g clamping	55 g/m	57 g/m				

CONFORMITIES AND CERTIFICATIONS

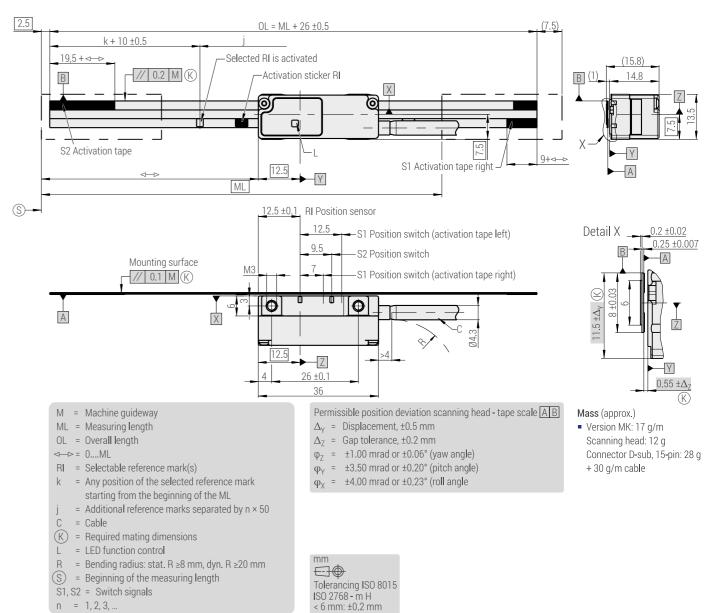
RoHS	2011/65/EU, 2015/863/EU
EMV	2014/30/EU
Product-Certifications	UL, CSA, EN, IEC 61010-1

MS 15 MK

Steel tape scale with adhesive tape

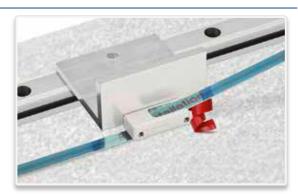


Dimensions, mounting tolerances:



Tape mounting tool **TMT MS 15 MK** (optional)
For safe and precise mounting of the steel tape scale.

- Mount TMT MS 15 MK instead of the MS 15 scanning head.
- Thread steel tape scale (version MK) and move along the scale length
- Remove TMT MS 15 MK, mount MS 15 scanning head.



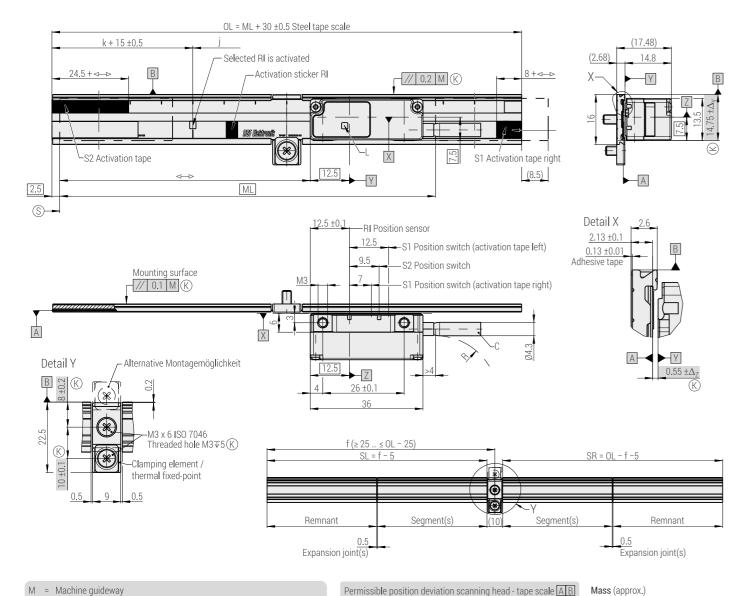


MS 15 MP

- Steel tape scale in aluminum carrier with clamping element
- Clamping element bolted
- Carrier with adhesive tape



Dimensions, mounting tolerances:



- M = Machine guideway
- ML = Measuring length
- OL = Overall length
- → = 0....ML
- RI = Selectable reference mark(s)
- k = Any position of the selected reference mark from the beginning of the ML
- = Additional reference marks spaced every n x 50
- = OL/2 (standard); any position of the clamping element (optional)
- C = Cable
- K = Required mating dimensions
- L = LED function control
- R = Bending radius: stat. R ≥8 mm, dyn. R ≥20 mm
- S = Beginning of the measuring length
- S1, S2 = Switch signal
- n = 1, 2, 3 ...

 Δ_{V} = Displacement, ±0.5 mm Δ_7 = Gap tolerance, ±0.2 mm $\phi_Z = \pm 1.00 \text{ mrad or } \pm 0.06^{\circ} \text{ (yaw angle)}$

 φ_{Y} = ±3.50 mrad or ±0.20° (pitch angle)

 ϕ_X = ±4.00 mrad or ±0.23° (roll angle

Mass (approx.)

- Version MP: 90 g/m
- + 2 g clamping element Scanning head: 12 g Connector D-sub, 15-pin: 28 g
- + 30 g/m cable

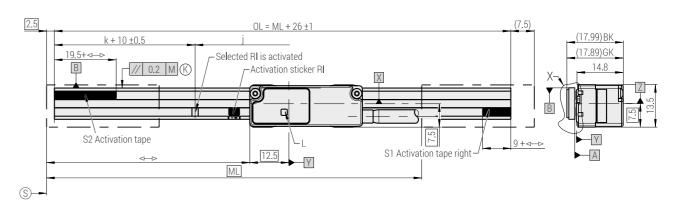
Tolerancing ISO 8015 ISO 2768 - m H < 6 mm: ±0.2 mm

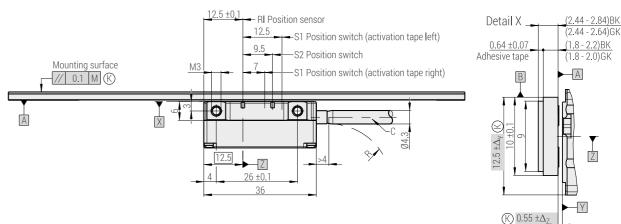
MS 15 GK, BK

- GK: Glass scale with adhesive tape
- BK: Glass ceramic scale with adhesive tape



Dimensions, mounting tolerances:





M = Machine guideway

ML = Measuring length

OL = Overall length

<---> = 0....ML

RI = Selectable reference mark(s)

k = Any position of the selected reference mark from the beginning of the ML

= Additional reference marks spaced every n x 50

C = Cable

K = Required mating dimensions

L = LED function control

R = Bending radius: stat. R ≥8 mm, dyn. R ≥20 mm

S = Beginning of the measuring length

S1, S2 = Switch signal

n = 1, 2, 3, ...

BK = Glass ceramic scale with adhesive tape

GK = Glass scale with adhesive tape

Permissible position deviation scanning head – scale AB

 $\Delta_{\rm v}$ = Displacement, ±0.5 mm

 Δ_{Z} = Gap tolerance, ±0.2 mm

 $\varphi_Z = \pm 1.00 \text{ mrad or } \pm 0.06^{\circ} \text{ (yaw angle)}$

 $\phi_Y = \pm 3.50 \text{ mrad or } \pm 0.20^{\circ} \text{ (pitch angle)}$ $\varphi_{x} = \pm 4.00 \text{ mrad or } \pm 0.23^{\circ} \text{ (roll angle)}$

Mass (approx.)

- Version BK: 57 g/m
- Version GK: 55 g/m Scanning head: 12 g Connector D-sub, 15-pin: 28 g
- + 30 g/m cable



Tolerancing ISO 8015

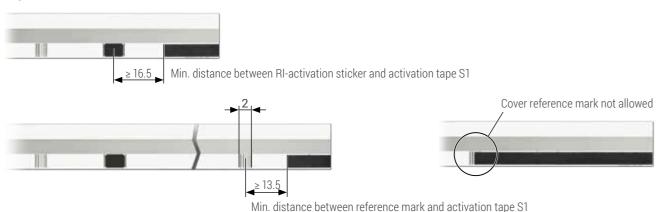


REFERENCE MARK (RI)- AND SWITCH POINTS-SELECTION

Reference mark (RI)-selection



NOTE



MS 15 BK, GK and MK selection of the switch points

S2 = Switch point signal S2 from beginning of ML

X2_L = Activation tape length

 $X2_1 = S2 + 19.5$

-

S1 = Switch point signal S1 before end of ML

X1_R = Activation tape length

 $X1_{R} = S1 + 9$

EXAMPLE

S2: 20 mm from beginning of ML \rightarrow X2_L = 39.5 mm

S1: 20 mm before end of ML \rightarrow X1_R = 29 mm



MS 15 MP selection of the switch points

S2 = Switch point signal S2 from beginning of ML

 $X2_{I}$ = Activation tape length

 $X2_{L} = S2 + 24.5$

S1 = Switch point signal S1 before end of ML

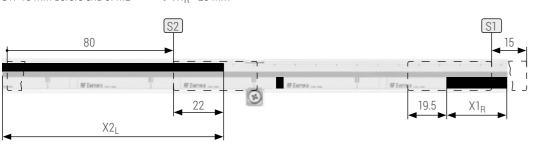
X1_R = Activation tape length

 $X1_{R} = S1 + 8$

EXAMPLE

S2: 80 mm from beginning of ML \rightarrow X2_L = 104.5 mm

S1: 15 mm before end of ML \rightarrow X1_B = 23 mm



INSPECTION OF FUNCTIONS

STATUS OF LED	INFORMATION	NOTE						
Without external test box								
Function-control main track								
■ LED displays GREEN	Counting signals very good	After successful mounting						
■ LED blinks GREEN	Counting signals good	At mounting not allowed \Rightarrow allowed during operation						
■ LED blinks RED	Counting signals out of tolerance → error	Check mounting, clean graduation carrier						
Function-control reference impulse RI		Only by passing the reference mark						
■ LED blinks BLUE	RI within tolerance							
■ LED blinks RED	RI out of tolerance	Check mounting, clean graduation carrier						
With external test box								
Function-control main track								
LED displays GREEN	Scanning head supplied with power	Evaluation of counting signals via LED not active						
Function-control reference impulse RI		Only by passing the reference mark						
■ LED blinks BLUE	RI within tolerance							
■ LED blinks RED	RI out of tolerance	Check mounting, clean graduation carrier						

Note! If the scanning head passes a further reference mark within 0.5 s the information of the reference mark will not be stated by the function control. Thus the information of the incremental signals will also be displayed at high traversing speed and/or many reference marks.



EXTERNAL TESTING DEVICE PWT 101

Even though the MS 15 linear encoders allow large mechanical mounting tolerances, it is recommended to control the function of counting signals and reference impulse.

The signals can be controlled directly via the integrated LED functioncontrol or connected to an oscilloscope and checked for conformity with signal specifications. The last mentioned method requires some effort.

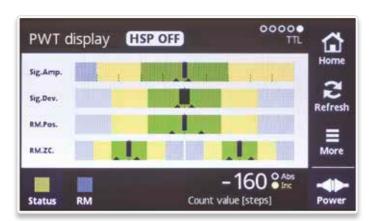
The PWT 101 is a testing device for checking the function and adjustment of RSF Elektronik encoders. At encoders with pin assignment according to RSF standard (compare page 05) the pinout adapter PA2 must be used additionally. At alternative pin assignments other pinout adapters could be necessary.

Thanks to its compact dimensions and robust design, the PWT 101 is ideal for mobile use. A 4.3-inch touchscreen provides for display and operation.

Available functions

The performance range of the PWT 101 can be expanded by firmware update. Appropriate firmware files that can be imported to the PWT 101 through a memory card (not included in delivery) will be made available at www.heidenhain.de.





FURTHER PRODUCTS







MCR 15 | MCS 15

Absolute modular angle encoders with small dimensions

- Diverse serial interfaces
- Status display directly at the scanning head via LED function
- Easy mounting as a result of large mounting tolerances
- High insensitivity against contaminations
- Possible drum diameter (TTR): 50.00 mm to 350.23 mm (outside)
- Possible scanning diameter (MBR):
 59.93 mm to 350.23 mm (outside)
- Steel tape scale (MSS) from Ø 75 mm

MSR 15 | MSS 15

Incremental modular angle encoders with small dimensions

- Quality of the scanning signals is directly visible at the scanning head via a tricolored LED function
- Easy mounting as a result of large mounting tolerances
- High insensitivity against contaminations
- Possible drum diameter (TTR):
 50.00 mm to 350.23 mm (outside)
- Possible scanning diameter (MBR):
 59.93 mm to 350.23 mm (outside)
- Steel tape scale (MSS) from Ø 75 mm

MSR 45

Modular angle encoders with steel tape scale various versions

- Full-circle or segment version
- Grating period: 200 μm
- Accuracy of the grating (stretched): ±30 µm/m
- High permissible rotational speed resp. circumferential speed
- Integrated subdividing: up to times 100
- Possible diameter:
 Full-circle from Ø 146.99 mm
 Segment from Ø 150 mm







MC 15

Absolute linear encoders with status display

- Divers serial interfaces
- Status display directly at the scanning head via LED function
- Easy mounting as a result of large mounting tolerances
- High insensitivity against contaminations
- Max. measuring length
 Steel tape scale: 10 000 mm

MS 25

Exposed linear encoder with and without integrated mounting control

- Easy mounting; no test box or oscilloscope needed
- Quality of the scanning signals is directly visible at the scanning head via a tricolored LED function
- Two independent switch tracks for individual special functions
- Position of reference mark selectable by customer
- High insensitivity against contamination
- High permissible traversing speedIntegrated subdividing:
- up to times 200

 Max. measuring length
 Glass scale: 3140 mm
 Steel tape scale: 20 000 mm

MS 45

Exposed scanning linear encoders with integrated mounting control

- Easy mounting; no test box or oscilloscope needed
- Quality of the scanning signals is directly visible at the scanning head via a tricolored LED function
- Flat dimensions
- Easy mounting due to large mounting tolerances
- High insensitivity against contamination
- High permissible traversing speed
- Integrated subdividing: up to times 100
- Max. measuring length: Steel tape scale: 30 000 mm

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Date 10/2021 ■ Art. No.1118281-03 ■ Doc. No. D1118281-08-A-01 ■ Technical adjustments in reserve!



Linear and Angle Encoders Precision Graduations

Certified acc. to ISO 9001 ISO 14001

